

Fetching GPS Coordinates using Raspberry Pi 4 Model B and Quectel EC200U via SMS in URL format

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Components Required:

7Semi EC200U-CN LTE 4G GPS GNSS Mini Industrial Modem with inserted SIM card



GPS External Active Antenna (3m) - SMA



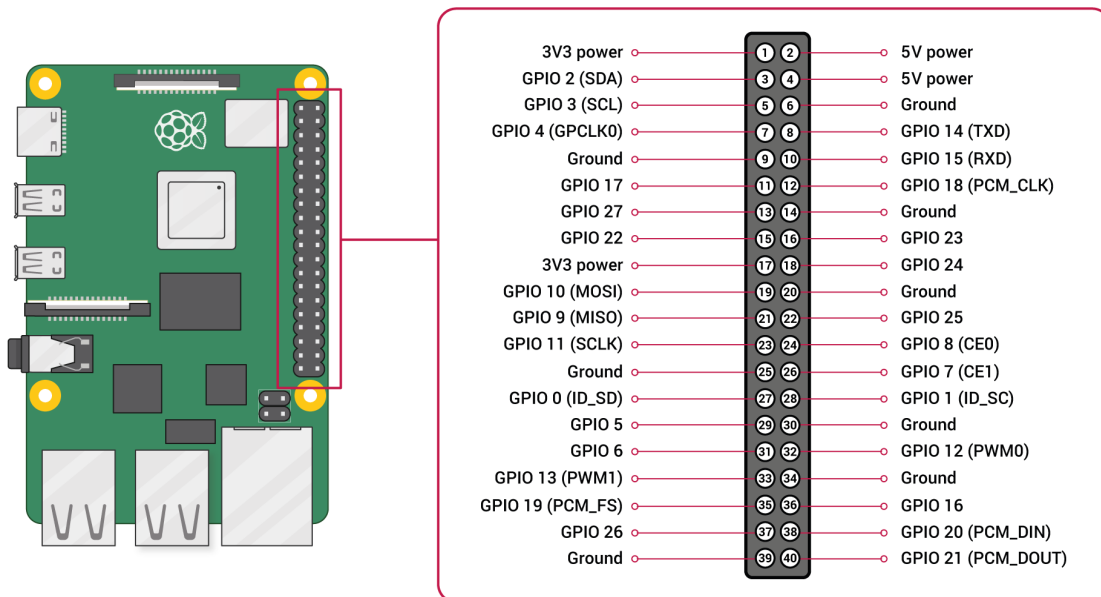
Raspberry Pi 4 Model-B



Software Requirements:

- VNC Viewer in your system to communicate with Raspberry Pi (Any alternative can be used)
- In Raspberry Pi:
 - Python
 - Pyserial Library (for serial communication)
 - Minicom (To check whether AT commands are working)

Connections:



Raspberry Pi	EC200U
GPIO 15 (RXD)	TX
GPIO 14 (TXD)	RX
GND	GND

- GPS Antenna to GNSS of EC200U
- Antenna to Main of EC200U
- Insert SIM card (If it is not inserted previously)
- Give power supply to your Pi through the switch board.
- Give power supply to EC200U through your System or Raspberry Pi



Python Code:

```

import os
import time
import serial

#Sending AT Commands
def send_at_command(ser, command, expected_response, timeout=2):
    ser.write((command + '\r').encode())
    time.sleep(timeout)
    response = ser.read_all().decode()
    if expected_response not in response:
        print(f"Error: {response}")
        return False, response
    return True, response

#To enable GPS
def enable_gps(ser):
    print("Enabling GPS...")
    success, response = send_at_command(ser, 'AT+QGPS=1', 'OK')
    if not success:
        print(f"Failed to enable GPS: {response}")
    else:
        print("GPS enabled successfully.")
    return success

#To disable GPS
def disable_gps(ser):
    print("Disabling GPS...")
    success, response = send_at_command(ser, 'AT+QGPSEND', 'OK')
    if success:
        print("GPS disabled successfully.")
    else:
        print(f"Failed to disable GPS: {response}")

#To get location coordinates and change it to URL format
def get_location(ser):
    if enable_gps(ser):
        print("Waiting for GPS fix...")
        max_retries = 10
        retry_interval = 10 # seconds
        for attempt in range(max_retries):
            success, response = send_at_command(ser, 'AT+QGPSLOC=2', '+QGPSLOC:',
timeout=5)
            if success:

```

```

        disable_gps(ser)
        lat_long = response.split(',')[1:3]
        if len(lat_long) == 2:
            return
f"http://maps.google.com/?q={lat_long[0]},{lat_long[1]}"
        else:
            print(f"Attempt {attempt + 1} failed: {response}")
            time.sleep(retry_interval)
        disable_gps(ser)
    return None

#To send SMS to a specific phone number
def send_sms(ser, phone_number, message):
    success, _ = send_at_command(ser, 'AT+CMGF=1', 'OK')
    if success:
        success, _ = send_at_command(ser, f'AT+CMGS="{phone_number}"', '>')
        if success:
            ser.write((message + '\x1A').encode())
            time.sleep(5)
            if 'OK' in ser.read_all().decode():
                return True
    return False

def main():
    phone_number = 'XXXXXXXXXX' # Replace with the recipient's phone number with
    ISD
    try:
        ser = serial.Serial('/dev/ttyS0', baudrate=115200, timeout=1)
        ser.dtr = True
    except serial.SerialException as e:
        print(f"Error opening serial port: {e}")
        return

    location_url = get_location(ser)
    if location_url:
        print(f"Location URL: {location_url}")
        if send_sms(ser, phone_number, location_url):
            print("SMS sent successfully")
        else:
            print("Failed to send SMS")
    else:
        print("Failed to get location")

    ser.close()

```

```
if _name_ == "_main_":
    main()
```

Procedure:

1. Make connections as mentioned above.
2. Display the pi using VNC viewer in your system.
3. Open terminal and type:

```
//To update and upgrade your raspberry pi, use
```

- `sudo apt update`
- `sudo apt upgrade`

```
//To manually test the AT commands to verify the GPS functionality
```

- `sudo apt-get install minicom`
- `sudo minicom -D /dev/ttyS0 -b 115200`

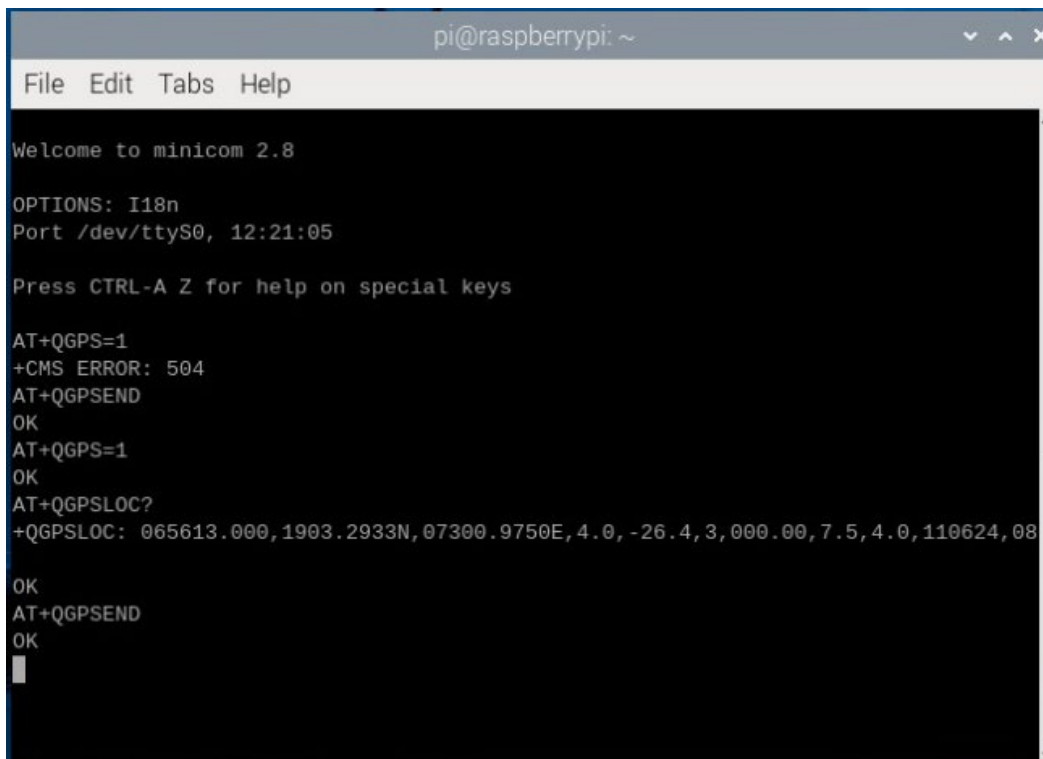
```
//Send AT commands in minicom:
```

- `AT` # Check if module responds with OK
- `AT+CPIN?` # Check if SIM is ready (should respond with +CPIN: READY)
- `AT+CSQ` # Check signal quality (should respond with +CSQ: <rss>,<ber>)
- `AT+CGATT?` # Check if attached to network (should respond with +CGATT: 1)
- `AT+QGPS=1` # Turn on GPS
- `AT+QGPSCFG="outport","usbmea"` # Optional: Configure output port if needed
- `AT+QGPSLOC?` # Request GPS location
- `AT+QGPSEND` # Turn off GPS

4. Write the python script in Thonny or IDLE.
5. Now, Run the python script and get location in SMS to the recipient's phone number.

Output:

Verifying AT commands in minicom:



```
pi@raspberrypi: ~  
File Edit Tabs Help  
Welcome to minicom 2.8  
OPTIONS: I18n  
Port /dev/ttyS0, 12:21:05  
Press CTRL-A Z for help on special keys  
AT+QGPS=1  
+CMS ERROR: 504  
AT+QGPSEND  
OK  
AT+QGPS=1  
OK  
AT+QGPSLOC?  
+QGPSLOC: 065613.000,1903.2933N,07300.9750E,4.0,-26.4,3,000.00,7.5,4.0,110624,08  
OK  
AT+QGPSEND  
OK
```

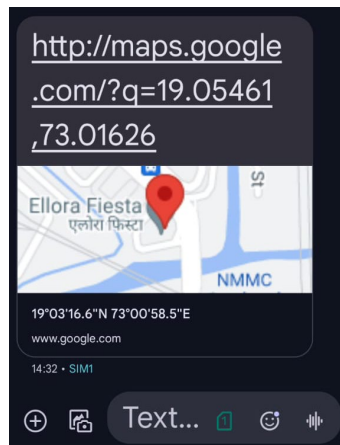
Python Shell Output:



```
Shell  
>>> %Run 'GPS location code.py'  
Enabling GPS...  
GPS enabled successfully.  
Waiting for GPS fix...  
Error: AT+QGPSLOC=2  
+CMS ERROR: 50  
  
Attempt 1 failed: AT+QGPSLOC=2  
+CMS ERROR: 50  
  
Error: AT+QGPSLOC=2  
+CMS ERROR: 516  
  
Attempt 2 failed: AT+QGPSLOC=2  
+CMS ERROR: 516  
  
Error: AT+QGPSLOC=2  
+CMS ERROR: 516  
  
Attempt 3 failed: AT+QGPSLOC=2  
+CMS ERROR: 516  
  
Disabling GPS...  
GPS disabled successfully.  
Location URL: http://maps.google.com/?q=19.05433,73.01543  
SMS sent successfully  
>>>
```

Local Python 3 • /usr/bin/python3

SMS Received:



Redirecting to Google Maps:

